RAPPER: REINFORCED RATIONALE-PROMPTED PARADIGM FOR NATURAL LANGUAGE EXPLANATION IN VISUAL QUESTION ANSWERING

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ABSTRACT

Natural Language Explanation (NLE) in vision and language tasks aims to provide human-understandable explanations for the associated decision-making process. In practice, one might encounter explanations which lack informativeness or contradict visual-grounded facts, known as *implausibility* and *hallucination* problems, respectively. To tackle these challenging issues, we consider the task of visual question answering (VQA) and introduce *Rapper*, a two-stage **R**einforced **Ra**tionale-**P**rom**pted** Paradigm. By knowledge distillation, the former stage of *Rapper* infuses rationale-prompting via large language models (LLMs), encouraging the rationales supported by language-based facts. As for the latter stage, a unique Reinforcement Learning from NLE Feedback (RLNF) is introduced for injecting visual facts into NLE generation. Finally, quantitative and qualitative experiments on two VL-NLE benchmarks show that *Rapper* surpasses state-of-the-art VQA-NLE methods while providing plausible and faithful NLE.

1 INTRODUCTION

Deep learning has achieved remarkable success in vision-language (VL) tasks such as visual reasoning (Suhr et al., 2017), visual question answering (VQA, Goyal et al., 2017), and visual entailment (Xie et al., 2019). Take VQA as an example, while these models exhibit impressive ability in inferring answer descriptions from the given image-question pairs, its decision-making process remains an unsolved problem. As a result, such a black-box manner severely restricts their applicability in certain real-world scenarios (e.g., medical VQA, Lin et al., 2023), where the interpretability of the learning model is crucial for establishing trustworthy systems. To tackle this long-standing challenge, some approaches adopt attention mechanisms (Anderson et al., 2018) or gradient-based activations (Selvaraju et al., 2017), focusing on highlighting image regions which are relevant to the associated prediction. However, such visual explanations might not be desirable for VL tasks (e.g., those beyond classification) due to the lack of reasoning process (Kayser et al., 2021; Sammani et al., 2022). As a result, Natural Language Explanation (NLE) has emerged as a potential alternative, which aims to interpret the underlying reasoning process by natural language descriptions.

To extend NLE for vision-language tasks (i.e., VL-NLE), Park et al. (2018) and Kayser et al. (2021) introduced the benchmarks for explaining the decision-making process with NLEs for VQA and visual entailment tasks, respectively. Subsequent VL-NLE works have evolved into two research lines. The first research line (Park et al., 2018; Marasović et al., 2020) focuses on how to improve their pipeline from an architecture perspective for training NLE generators within a fully supervised learning manner. On the other hand, Sammani et al. (2022) and Suo et al. (2023) emphasize the utilization of unlabeled pre-training data to enhance the language models' NLE capability.

Despite significant advancements, most existing VL-NLE works require training in a full supervised manner. They might encounter problems where the explanations are irrelevant to the questions or contradictory to the established supporting facts (Majumder et al., 2021). The other potential concern



Figure 1: Comparison between (a) previous VQA-NLE paradigm and (b) our proposed reinforced rationale-prompted VQA-NLE paradigm of (*Rapper*). Instead of directly generating answer or explanation, *Rapper* learns plausible and faithful explanations which prompt the VQA model with improved performance.

is that the explanation is not related to the visual image (Ji et al., 2023). More specifically, the former problem is referred to as *implausibility*, while the latter is known as *hallucination*. Take visual input and question in Fig. 1 as an example, "Because there is a tower.' is an *implausible* explanation since it is irrelevant to question, and "Because the sun is big." is a *hallucinated* one since the sun is not visible in the image. Although these issues have been recently studied in the NLE community (Zhao et al., 2023; Turpin et al., 2023), they remain unexplored in the field of VL-NLE. As a result, generating *plausible* yet *faithful* NLEs for elucidating vision-language models continues to pose a crucial challenge.

Recently, rationale-based prompting techniques have been manifested to improve the capability of Large Language Models (LLMs) on complex reasoning tasks (Wei et al., 2022; Liu et al., 2022b). Such techniques involve elicitation of rationales from LLMs, producing knowledge-riched or fact-based intermediate to facilitate the reasoning capability of language model. Thus, these prompting manners are emerging as promising solutions for NLE (Zhao et al., 2023; Krishna et al., 2023). These rationale-prompting paradigms have been further extended to multi-modal regimes such as mm-CoT (Zhang et al., 2023) and mm-ReAct (Yang et al., 2023). However, mm-CoT (Zhang et al., 2023) relies on the ground-truth rationales for training, while mm-ReAct (Yang et al., 2023) have potential hallucinated outputs due to the information loss when converting visual signals into text for ChatGPT API call understanding.

In this paper, we propose *Reinforced Rationale-Prompted Paradigm* (*Rapper*) for providing accurate answers for VQA with sufficient NLE, which are plausible and faithful. As depicted in Fig. 1(b), our *Rapper* learns to exploit knowledge learned from LLM and incorporate the corresponding visual content from input images into *rationales* through two stages. Without observing any ground truth rationale during training, the first stage utilizes a knowledge distillation process to introduce LLM for enriching the rationales with supporting facts, encouraging NLE to be factual and plausible. The subsequent stage of *Reinforcement Learning from NLE Feedback* (RLNF) further exploits the answer-explanation feedback to enforce the produced rationales associated with both question and visual inputs, allowing faithful NLE.

We now summarize the contributions of this work below:

- A reinforced rationale-prompted paradigm, *Rapper*, is proposed for plausible and faithful NLE generation in VQA. This is achieved through two proposed stages: knowledge distillation process from LLM and *Reinforcement Learning from NLE Feedback (RLNF)*.
- In *Rapper*, we first advance LLM and perform knowledge distillation. This results in predicted rationales being based on language-based facts, which prompt the VQA model for plausible NLE.
- To align NLE with the visual input, we introduce *Reinforcement Learning from NLE Feedback* (RLNF) to *Rapper*, which utilizes the answer-explanation feedback as rewards and prompts the VQA model with predicted rationales for faithful NLE.

• Our *Rapper* achieves new state-of-the-art performance for both VQA-X (Park et al., 2018) and e-SNLI-VE (Kayser et al., 2021) on NLE generation. We also demonstrate that *Rapper* outperforms existing VQA-NLE works with reduced implausibility and hallucination.

2 Related work

Plausible and Faithful Natural Language Explanation Research on plausibility and faithfulness in NLE (Majumder et al., 2021; King et al., 2022; Gou et al., 2023; Stacey et al., 2023) has garnered wide attention, particularly due to the evolution of Large Language Models (LLMs) and chain-of-thought (CoT) prompting techniques (Wei et al., 2022). Notably, the method of integrating external knowledge databases for fact generation or retrieval has been proven effective in enhancing the plausibility and faithfulness of NLEs (Majumder et al., 2021; Stacey et al., 2023). Based on this advancement, some recent approaches, such as the *verify-then-correct* pipeline by Gou et al. (2023) and novel decoding strategies proposed by Lan et al. (2023) and King et al. (2022), aim to mitigate hallucination in textual outputs. However, these works typically focus on isolated single text modality or rely on static external knowledge databases, limiting its scalability to multimodal data.

Natural Language Explanation for Vision-Language Tasks Most existing VL-NLE works (Wu & Mooney, 2018a; Park et al., 2018; Marasović et al., 2020; Kayser et al., 2021) generate explanations in a predict-then-explain fashion. Specifically, an answer is first predicted by a pre-trained VL model (e.g., UNITER (Chen et al., 2020) or Oscar (Li et al., 2020)), followed by the generation of the corresponding explanation via a separate language decoder (e.g., GPT2 (Radford et al., 2019)). As the answer and explanation are predicted separately, the explanation offen contains irrelevant or contradictory descriptions of the given visual information, struggling to faithfully represent the underlying reasoning process. Recently, NLX-GPT (Sammani et al., 2022) proposes to jointly generate the answer and explanation to be consistent with the predicted answer. Although the above approaches have been shown to mitigate the hallucination issue, it is not clear how their NLE is established upon supporting facts or taking the visual input into consideration. Therefore, how to tackle the potential implausibile or hallucinated NLE remains a challenging task.

Reinforcement Learning for Language Models Several research works have explored RL and view it as the key component to enhance models across vision-language tasks such as image captioning (Rennie et al., 2017), novel object captioning (NOC) (Yang et al., 2022), and VQA (Lu et al., 2022a; Fan et al., 2018; Liu et al., 2018). There has been a concentrated effort to align LMs with natural language (NL) feedback (Akyürek et al., 2023; Yang et al., 2022; Liu et al., 2022a) as well as non-NL feedback (Bai et al., 2022; Lu et al., 2022b). For example, Liu et al. (2022a) utilizes the probability of the correct answer as a reward to stimulate an auxiliary module to produce beneficial knowledge, thereby enhancing QA-task performance. Similarly, Yang et al. (2022) employs a CIDEr optimization strategy to enhance the caption with sufficiently visual fidelity in the task of novel object captioning. Despite of their effectiveness, their RL framework or NL-feedback approaches cannot be easily applied for VL-NLE tasks.

3 PROPOSED METHOD

3.1 PROBLEM FORMULATION

Given a VQA input X = (V, Q) consisting of an input image V and a textual input Q (i.e., question), our goal is to predict the answer \hat{A} and the corresponding explanation \hat{E} (denoted as $\hat{Y} = (\hat{A}, \hat{E})$) via a reasoning module M. In order to encourage M to provide correct answer with plausible and faithful explanation, we propose a **R**einforced **Rationale-Prompted Paradigm** (Rapper) scheme, which learns an additional rationale generator G to jointly exploit the supporting facts from LLMs and the visual content observed from the conditioned image into rationales. Note that only the ground truth A and E are available during training, not the rationales. As depicted in Fig. 2, the learning of Rapper is decomposed into: (A) Knowledge Distillation from LLM (Sec. 3.2), and (B) Reinforcement learning from NLE Feedback (RLNF) (Sec. 3.3), which trains rationale generator G for providing auxiliary intermediates when predicting $\hat{Y} = (\hat{A}, \hat{E})$.



Figure 2: Overview of *Rapper*. *Rapper* involves two training stages: (A) *Knowledge distillation* introduce the rationales R'_p from LLM by offering established facts, facilitating the generation of plausible NLEs from the reasoning module M. (B) *Reinforcement learning from NLE feedback* (*RLNF*) further refines the rationales from R' to R by incorporating visual information, encouraging generation of faithful NLEs from M.

3.2 PLAUSIBLE NLE GENERATION

Since VQA-NLE models typically rely on ground truth answers and explanations for training, it is not clear whether the underlying visual and language knowledge are exploited to support the predicted outputs. In the first stage of *Rapper*, we propose to leverage powerful *reasoning* capability inherent in LLM for plausible NLE generation. As depicted in Fig. 2(A), we propose to learn a rationale generator G by utilizing knowledge distillation from LLM (e.g., LLaMA-65B (Touvron et al., 2023)). This would have the reasoning module M elaborate the conditioned rationales before answering and explaining and encourage plausible NLE. We now detail this learning stage.

3.2.1 KNOWLEDGE DISTILLATION FOR FACTED-BASED RATIONALE GENERATION

With the recent success of LLMs showing great capability for generating rationale prompts as intermediate reasoning steps and knowledge (Wei et al., 2022; Kojima et al., 2022; Liu et al., 2022b) for reasoning task, we propose to advance the guidance of pre-trained LLMs to acquire such knowledge, so that supporting facts or knowledge can be exploited and serve as rationales for VL-NLE. Since no ground-truth rationales are available, we leverage the LLM to produce rationales as pseudo ground truth for training our rationale generator G. Inspired by Liu et al. (2022a;b) and Min et al. (2022), we elicit pseudo rationale r_p from LLM with a task-specific set of few-shot demonstrations (see Sec. A.5 for details) as follows:

$$R_p = \{r_p \mid r_p \sim P_{LLM}(y, q)\},\tag{1}$$

where y is the ground-truth answer-explanation pair, q is question, P_{LLM} denotes the LLM in an autoregressive manner, r_p is the sampled pseudo rationale from P_{LLM} , and thus R_p is the set of all r_p .

However, the above pseudo rationales may be redundant, noisy or lengthy, which would not be desirable for subsequent NLE tasks (Li et al., 2023b). Thus, we apply a post-processing mechanism to filter pseudo rationales R_p to R'_p . To be specific, we apply a round-trip consistency by answering

the input question on the pseudo rationales with a pre-trained question-answering (QA) model F^{1} . The pseudo rationale is retained when the matching score between the ground-truth answer and the answer predicted by F exceeds a predetermined threshold τ . This matching score is quantified with the token-level F1 score (Wang et al., 2020). Thus, the process of collecting the filtered pseudo rationales R'_{p} is formulated as follows:

$$R'_p = \{r_p \mid \texttt{F1-score}(\tilde{a}, a) \ge \tau, \ \tilde{a} \sim P_F(Q, r_p), r_p \in R_p\},\tag{2}$$

where a is the ground truth answer, \tilde{a} is the answer predicted by F based on the pseudo rationale, and P_F denotes the pre-trained QA model F in an autoregressive fashion.

With the above R'_p serving as psuedo ground truth, we are able to train the rationale generator G with the distillation loss \mathcal{L}_G described below:

$$\mathcal{L}_G = -\sum_{t=1}^T \log(p_G(r'_{p,t}|r'_{p,0:t-1}, x)), \tag{3}$$

where $r'_p \in R'_p, T = |r'_p|$, and $x = \{v, q\} \in X$.

3.2.2 PROMPTING BY FACT-BASED RATIONALE FOR PLAUSIBLE NLE

With rationales R'_p better aligned with the facts, we can proceed to the training of the reasoning module M for NLE generation. We note that, since rationales R'_p are in the form of natural language, our the reasoning module M (which is also based on visual-language model) would be able to interpret them. Thus, in addition to the image-question pair X as the inputs to the reasoning module M, the derived pseudo rationales R'_p are further viewed as input prompts, which provide fact-supporting conditions when training M to perform VQA-NLE. As a result, we train M by calculating the reasoning loss L_M as follows:

$$\mathcal{L}_M = -\sum_{t=1}^T \log(p_M(y_t | y_{0:t-1}, r'_p, x)).$$
(4)

In the above cross-entropy loss, $y = [a; e] \in Y$ is the concatenation of the ground-truth answer a and explanation e.

3.3 FAITHFUL NLE GENERATION

Although the above knowledge distillation process based on LLM introduces plausibility into our rationale generation, the predicted rationales might not be related to the visual input and thus encounter the hallucination problem. To tackle this issue, we introduce a novel technique of *Reinforcement Learning from NLE Feedback* (RLNF). This learning strategy is to encourage the rationale generator G to fully exploit multimodal input data, so that the output rationales are not only plausible but also faithful. Once G produces faithful rationales, we can fine-tune the reasoning module M for plausible yet faithful NLE.

3.3.1 RLNF FOR INJECTING VISUAL FACTS

To address the potential hallucination issue, we propose *Reinforcement Learning from NLE Feedback* (*RLNF*) by enforcing rationale generator *G* to derive the visual facts from the input image into rationales. To achieve this, we define a reward function via RL that penalizes the fact-based but hallucinated rationales R', while rewarding the rationales R that contain both established facts and visual content, as depicted in Fig. 2(B). To achieve this, we design our reward \mathbf{r}_{total} to be the addition of answer scores \mathbf{r}_{ans} and the explanation score \mathbf{r}_{exp} , which are the average predicted probability of the ground-truth answer and CIDEr score (Vedantam et al., 2015), respectively. For the answer score, inspired by and following Kadavath et al. (2022), we maximize the answer score to assess the faithfulness of the predicted explanation. This maximization enforces the rationale

¹In the implementation, we follow (Changpinyo et al., 2022) and use UnifiedQA (Khashabi et al., 2022) as the pre-trained QA model.

| Algorithm 1 Training RAPPER | |
|--|--|
| Input: Rationale generator G, reasoning module M, LLM P_{LLM} and pre-traine Data: Image-question pairs $X = \{x^i\}_{i=1}^N$, and answer-explanation pairs $Y =$ | ed QA model P_F $\{y^i\}_{i=1}^N$ |
| /* Stage(A): KD for Plausible NLE Generation */ $R_p \leftarrow$ Collect pseudo rationales (Eq. equation 1); $R'_p \leftarrow$ Get filtered pseudo rationales from R_p (Eq. equation 2); | ⊳ Section 3.2.1 |
| $G \leftarrow$ Update G with \mathcal{L}_G (Eq. equation 3); $M \leftarrow$ Update M with \mathcal{L}_M (Eq. equation 4); | ⊳ Section 3.2.2 |
| /* Stage(B): RLNF for Faithful NLE Generation */ $G \leftarrow$ Update G with \mathbb{R}_{total} (Eq. equation 8); $M \leftarrow$ Update M with \mathcal{L}_M (Eq. equation 10); | ▷ Section 3.3.1 ▷ Section 3.3.2 |
| Output: G_{θ}, M_{ϕ} | |

generator G to inject more visual content into the rationale because the reasoning module M need more visual clues to correctly answer the question. Therefore, this process transform R' to R, and simultaneously provide the M with more visual fact-based rationale R to enable the explanation with sufficient faithfulness. On the other hand, the explanation score r_{exp} is (i.e., specifically CIDEr score) to maintain the plausibility of NLE after the first training stage. As a result, the reward r_{total} is formulated as follows:

$$\mathbf{r}_{total}(x, a, e, \hat{e}, r) = \mathbf{r}_{ans}(a, x, r) + \mathbf{r}_{exp}(e, \hat{e}),\tag{5}$$

$$\mathbf{r}_{ans}(a, x, r) = \mathcal{Z}(P_{M_{\phi}}(a \mid x, r)), \tag{6}$$

$$\mathbf{r}_{exp}(e, \hat{e}) = \mathcal{Z}(\texttt{CIDEr}(e, \hat{e})),\tag{7}$$

where $x = \{v, q\}$ is the input image-question pair, a denotes the ground-truth answer, e denotes the ground-truth explanation, \hat{e} is the predicted explanation from M, and $r \in R$ is the sampled rationales from G.Notably, Z is an input-specific normalization function that follows Deng et al. (2022) to normalize reward for stabilizing the RL training process.

RLNF Formulation Our RLNF employs Proximal Policy Optimization (PPO) (Schulman et al., 2017) as the RL algorithm. As the policy model updated, the rationale generator G is to maximize the following reward \mathbb{R}_{total} :

$$\max\{\mathbb{R}_{total}(x, a, e, \hat{e}, r)\}, r \sim \prod_{t=1}^{T} P_G(w_t | w_{< t}),$$
(8)

where $r = \{w_i\}_{i=0}^T$, T = |r|, and $x = \{v, q\}$. However, we need to ensure the generated rationales are understandable by humans and do not deviate too far from the distilled knowledge. To achieve this, we add a KL penalty term between the learned policy θ and the initial policy θ_{init} after the knowledge distillation phase. Therefore, the overall reward is defined as:

$$\mathbb{R}_{total}(x, a, e, \hat{e}, r) = \mathbb{r}_{total}(x, a, e, \hat{e}, r) - \alpha \log \frac{p_G(r|x; \theta)}{p_G(r|x; \theta_{init})},\tag{9}$$

where $\mathbb{R}_{total}(x, a, e, \hat{e}, r)$ is the reward in Eq. 5.

3.3.2 PROMPTING BY VISUAL-FACT-BASED RATIONALE FOR FAITHFUL NLE

Once the rationale generator G is trained with the introduced RLNF, it is encouraged to produce visual fact-based rationales R that are encapsulated with established facts and visual content from visual input. Again, since R are natural language prompts, they are inherently interpretable by our reasoning module M. Therefore, for the given image-question pairs X, we utilize R as part of input prompts during the reasoning process of M. This ensures the NLEs from M retain plausibility because of the established supporting facts lies in R, together with the enhanced faithfulness because

of the derived visual content embedded in R. We optimize M to achieve this with the reasoning loss \mathcal{L}_M defined as follows:

$$\mathcal{L}_{M} = -\sum_{t=1}^{T} \log(p_{M}(y_{t}|y_{0:t-1}, r, x)),$$
(10)

where $r \in R$, $x = \{v, q\} \in X$, and $y = [a; e] \in Y$, which is the concatenated ground-truth answer a and explanation e sequence.

Therefore, through the complete *Rapper* training process as outlined in Algorithm 1, VQA-NLE tasks would be successfully enabled with adequate plausibility and faithfulness.

3.4 INFERENCE

At inference time, for a given input image-question pair $x \in X$, we first generate rationale r on the fly from the rationale generator G:

$$r = \{ w_i \mid w_i \sim P_G(w_{\leq i}, x); i = 0, \dots, n \},\$$

where $r = \{w_i\}_{i=0}^n$ is the sampled rationale, n = |r|, and $x = \{v, q\}$. Subsequently, we prompt the reasoning module M by concatenating the predicted rationale \hat{r} with the image-question pair x for outputting the final answer and explanation sequence \hat{y} . This can be formulated as:

$$\hat{y} = [\hat{a}; \hat{e}] = \{z_i \mid z_i \sim P_M(z_{< i} \mid x, r); i = 0, \dots, m\},\$$

where $m = |\hat{y}|$, and $\hat{y} = \{z_i\}_{i=0}^m$ is the concatenated answer and explanation, denoted as $[\hat{a}; \hat{e}]$.

4 EXPERIMENTS

4.1 DATASET AND SETUP

We follow (Kayser et al., 2021; Sammani et al., 2022; Suo et al., 2023) and consider two VL-NLE datasets. VQA-X (Park et al., 2018) builds upon VQAv2 dataset (Goyal et al., 2017). It is composed of 32.3K samples, divided into 29K for training, 1.4K for validation, and 1.9K for testing. e-SNLI-VE (Kayser et al., 2021) builds upon e-SNLI dataset (Camburu et al., 2018), consisting of 43K image-hypothesis pairs, divided into 40K for training, 1.4K for validation, and 1.6K for testing.

Rapper is consists of a rationale generator G and a reasoning module M, are both initialized from the pretrained image captioning model (Li et al., 2023a). The LLM for knowledge distillation during stage(A) is LLaMA-65B (Touvron et al., 2023). More implementation details are shown in Sec. A.1.

4.2 EVALUATION METRICS

For NLE evaluation, we use BLEU@N (Papineni et al., 2002), METEOR (Banerjee & Lavie, 2005), ROUGE-L (Lin, 2004), CIDEr (Vedantam et al., 2015), and SPICE (Anderson et al., 2016) as the metrics, while using VQA accuracy to evaluate predicted answers. To evaluate the degree of plausibility and faithfulness of explanations, we measure them with CIDEr/SPICE and RefCLIPScore Hessel et al. (2021), respectively. In addition, we build human evaluation for explanation on plausibility and faithfulness since automatic metric measures not always reflect the correctness and logicality. Please refer to Appendix A.3 for the details of our human evaluation process.

Plausibility To quantitatively evaluate explanation plausibility, we employ CIDEr and SPICE scores. CIDEr measures the similarity between the generated explanation and human-written ground truth sentences, capturing human consensus by introducing tf-idf weight (Vedantam et al., 2015). On the other hand, SPICE converts sentences into semantic scene graphs, allowing evaluation to break grammatical constraints and thus closely resembling human judgment (Anderson et al., 2016).

Faithfulness We adopt RefCLIPScore, which computes the harmonic mean of CLIPScore (Hessel et al., 2021) and maximal reference cosine similarity, thereby encapsulating the correlation between the explanation and its reference. As noted by Hessel et al. (2021), RefCLIPScore surpasses prior metrics in correlating with human judgment for hallucination detection.

| | VQA-X | | | | | | | | |
|--------------------------------|-----------|------|------|------|--------|---------|-------|-------|----------|
| Method | B@1 | B@2 | B@3 | B@4 | METEOR | ROUGE-L | CIDEr | SPICE | Accuracy |
| PJ-X (Park et al., 2018) | 57.4 | 42.4 | 30.9 | 22.7 | 19.7 | 46.0 | 82.7 | 17.1 | 76.4 |
| FME (Wu & Mooney, 2018b) | 59.1 | 43.4 | 31.7 | 23.1 | 20.4 | 47.1 | 87.0 | 18.4 | 75.5 |
| RVT (Marasović et al., 2020) | 51.9 | 37.0 | 25.6 | 17.4 | 19.2 | 42.1 | 52.5 | 15.8 | 68.6 |
| QA-only (Kayser et al., 2021) | 51.0 | 36.4 | 25.3 | 17.3 | 18.6 | 41.9 | 49.9 | 14.9 | - |
| e-UG (Kayser et al., 2021) | 57.3 | 42.7 | 31.4 | 23.2 | 22.1 | 45.7 | 74.1 | 20.1 | 80.5 |
| NLX-GPT (Sammani et al., 2022) | 64.2 | 49.5 | 37.6 | 28.5 | 23.1 | 51.5 | 110.6 | 22.1 | 83.07 |
| S3C (Suo et al., 2023) | 64.7 | 50.5 | 38.8 | 30.7 | 23.9 | 52.1 | 116.7 | 23.0 | 85.6 |
| Rapper (ours) | 65.5 | 51.6 | 40.5 | 31.8 | 24.3 | 52.9 | 124.0 | 24.5 | 87.25 |
| | e-SNLI-VE | | | | | | | | |
| Method | B@1 | B@2 | B@3 | B@4 | METEOR | ROUGE-L | CIDEr | SPICE | Accuracy |
| PJ-X (Park et al., 2018) | 29.4 | 18.0 | 11.3 | 7.3 | 14.7 | 28.6 | 72.5 | 24.3 | 69.2 |
| FME (Wu & Mooney, 2018b) | 30.6 | 19.2 | 12.4 | 8.2 | 15.6 | 29.9 | 83.6 | 26.9 | 73.7 |
| RVT (Marasović et al., 2020) | 29.9 | 19.8 | 13.6 | 9.6 | 18.8 | 27.3 | 81.7 | 32.5 | 72.0 |
| QA-only (Kayser et al., 2021) | 29.8 | 19.7 | 13.5 | 9.5 | 18.7 | 27.0 | 80.4 | 32.1 | - |
| e-UG (Kayser et al., 2021) | 30.1 | 19.9 | 13.7 | 9.6 | 19.6 | 27.8 | 85.9 | 34.5 | 79.5 |
| | | | | | | | | | |
| NLX-GPT (Sammani et al., 2022) | 37.0 | 25.3 | 17.9 | 12.9 | 18.8 | 34.2 | 117.4 | 33.6 | 73.91 |

Table 1: Quantitative NLE comparisons of *filtered* results (i.e., NLE evaluation conditioned on correct answers) on VQA-X and e-SNLI-VE.

| | Unfiltered | | | | Filtered | | | | | | |
|----------------------|------------|--------|------------|-------|----------|------|--------|----------|-------|-------|----------|
| Method | B@4 | METEOR | ROUGE-L | CIDEr | SPICE | B@4 | METEOR | ROUGE-L | CIDEr | SPICE | Accuracy |
| Rapper | 30.0 | 23.3 | 51.3 | 116.0 | 23.2 | 31.8 | 24.3 | 52.9 | 124.0 | 24.5 | 87.3 |
| - RLNF | 29.4 | 23.6 | 51.2 | 113.0 | 23.0 | 31.2 | 24.5 | 52.5 | 120.2 | 24.2 | 86.6 |
| - RLNF - KD | 27.1 | 21.8 | 49.7 | 103.2 | 20.7 | 29.3 | 23.0 | 51.6 | 112.1 | 22.3 | 85.0 |
| | | | Unfiltered | | | | | Filtered | | | |
| Method | B@4 | METEOR | ROUGE-L | CIDEr | SPICE | B@4 | METEOR | ROUGE-L | CIDEr | SPICE | Accuracy |
| Rapper | 30.0 | 23.3 | 51.3 | 116.0 | 23.2 | 31.8 | 24.3 | 52.9 | 124.0 | 24.5 | 87.3 |
| Rapper w/o filtering | g 28.5 | 22.7 | 50.8 | 110.6 | 22.2 | 30.1 | 23.4 | 52.1 | 116.7 | 23.4 | 86.4 |

Table 2: Ablation studies of the proposed training schemes (up) and the filtering mechanism for knowledge distillation (bottom). We compare the performances in both filtered and unfiltered settings.

4.3 QUANTITATIVE ANALYSIS

NLE evaluation. In Table 1, Table 5, and Table 6, we demonstrate that *Rapper* outperform previous state-of-the-art methods in NLE-related metrics on both VQA-X and e-SNLIV-VE datasets, with *filtered* and *unfiltered* settings. The *filtered* setting in Table 1 considers the explanations that are associated with correct answers. Conversely, the *unfiltered* setting in Table 5 and Table 6 in Appendix A.2 indicates evaluations of explanations without considering the correctness of the corresponding answers.

Plausibility & faithfulness of NLE. We assess the plausibility and faithfulness in NLE through CIDEr/SPICE (in Table 1), RefCLIPScore (in Table 3), and human evaluation (in Table 4). In table 1, we demonstrate that *Rapper* outperforms previous state-of-the-art methods in NLG metrics on both VQA-X and e-SNLI-VE benchmarks, underscoring its superiority in generating plausible explanations.

| Method | RefCLIPScore(↑) |
|------------------------------|-----------------|
| Much recent VL-NLE works | |
| NLX-GPT | 64.06 |
| S3C | 65.09 |
| Our stage-ablated approaches | |
| Rapper (w/o KD and w/o RLNF) | 66.00 |
| Rapper (w/o RLNF) | 65.66 |
| Rapper | 67.05 |

Table 3: Faithfulness evaluation on the VQA-X dataset under filtered setting. Note that a higher RefCLIPScore indicates less hallucination.

| Method | Plausibility (†) | Faithfulness (†) |
|----------------|------------------|------------------|
| NLX-GPT S3C | 0.771 0.797 | 0.795 0.811 |
| Rapper | 0.845 | 0.859 |

Table 4: Human evaluation on plausibility and faithfulness on VQA-X in the filtered setting.

On the other hand, in table 3, *Rapper*'s superior RefCLIPScore indicates fewer hallucinations and increased faithfulness over other VQA-NLE works, although the RefCLIPScore of *Rapper* (w/o RLNF) is lower due to the hallucinations introduced by knowledge distillation from LLM. Nonetheless, *Rapper* still successfully reduce hallucination after the RLNF training. This demonstrates the effectiveness of our proposed RLNF to enable the model to generate faithful NLEs. Lastly, through human evaluation in Table 4, we provide further human-perceived evidence for the effectiveness of *Rapper* for improved NLE generation.

| Multimodal Input | | (a) | (b) | (c) | | |
|---------------------|--|--|---|---|--|--|
| Methods | | Q: Is the table cluttered? GT A: No GT E: There is only a single vase with flowers on it | Q: Is this in an asian country? GT A: Yes GT E: there is an asian language used as text font in public | Q: What kind of animal is this? GT A: Sheep GT E: The animal is covered in thick wool | | |
| NLX-GPT | $\hat{A} \ \hat{E}$ | No There are no objects in the table | Yes There is a train on the tracks | Sheep It has a long face and long nose | | |
| $S^{3}C$ | $\hat{A} \ \hat{E}$ | No There are only <mark>a few</mark> items on it | Yes There is a train in the stations | Sheep It has a long snout and white fur | | |
| Rapper | $egin{array}{c} R \ \hat{A} \ \hat{E} \end{array}$ | The table is not cluttered because there is only one object on it No There is only one object on it | The presence of asian writing on the train suggests that it is in an asian country Yes There is asian writing on the train | A sheep is a type of animal that has wool on its body Sheep Its has wool on its body | | |

Figure 3: Visualization of output answers and explanations predicted by different methods. Note that words in red denote hallucinated explanations, and those in orange denote implausible ones. Words in blue denote faithful and plausible explanations to the input image-question pair.

Ablation on the proposed stages. In top of Table 2, we evaluate our two-stage approach: (A) KD from LLM and (B) RLNF. Compared to the *Rapper* baseline without KD and RLNF, our method enhances explanation plausibility and faithfulness, highlighting the importance of both stages.

Ablation on the "Filter" mechanism. In bottom of Table 2, our filtering mechanism in knowledge distillation stage outperforms the baseline *Rapper* without filtering, by effectively removing overly redundant and noisy pseudo rationales that could impair model performance.

Ablation studies of derived rationales. In Fig. 4, we demonstrate that introducing two proposed stages improves the quality of derived rationales, benefiting the VQA performance of vision-language large model. Specifically, we test whether mPLUG-Owl (Ye et al., 2023) can answer accurately when given a pair (image, question, and $x \in (None, R', R)$), where x = None indicates no rationales as input, x = R' indicates the rationales are from *Rapper* with KD training, and x = R indicates the rationales are from *Rapper* with both KD and RLNF training. Notably, we find that rationale quality improves progressively as we implement the stages we have proposed. This underscores the effectiveness of our designed stages in enhancing rationale quality.

4.4 QUALITATIVE EVALUATION



Figure 4: Ablation studies of derived rationales. Note the VQA accuracy on the VQA-X dataset is evaluated.

In Fig.3, we compare NLX-GPT(Sammani et al., 2022), S3C (Suo et al., 2023), and our *Rapper* on the VQA-X dataset. *Rapper* consistently produces more plausible explanations. For example, Fig.3(a) highlights ability of *Rapper* to derive visual facts, such as identifying a single object on the table, surpassing previous methods that might produce hallucinated explanations. Similarly, in Fig.3(b), *Rapper* offers plausible explanations like recognizing Asian writing, contrasting with the implausible outputs of prior methods. Additional results and ablation studies are in Appendix A.4.

5 CONCLUSION

In this paper, we proposed *Rapper*, a two-stage Reinforced Rationale-Prompted Paradigm for enabling NLE with sufficient plausible and faithful properties. Our *Rapper* uniquely distills language-based knowledge from LLM and utilizes RL with natural language feedback from the VQA task, so that the designed rationale generator is able to produce rationales with the aforementioned desirable properties. By prompting such predicted rationales into the reasoning module, we demonstrated that satisfactory VQA performances can be achieved. Compared to SOTA VQA-NLE methods, possible implausible or hallucinated explanations can be mitigated by our *Rapper*.

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